

# 1 GYRE stuff

## 1.1 Rotation inversion

First, let's gather some definitions. From GYRE's documentation,

$$U = \frac{d \ln m}{d \ln r} \quad (1)$$

$$= \frac{4\pi r^3 \rho}{m} \quad (2)$$

$$c_1 = \frac{r^3 M}{R^3 m} \quad (3)$$

$$\Rightarrow \frac{U}{c_1} = \frac{4\pi R^3 \rho}{M} \quad (4)$$

Now, reading from GYRE's code and re-arranging,

$$\frac{dE}{dx} = \frac{(\xi_r^2 + \lambda \xi_h^2) U x^2}{c_1} \quad (5)$$

$$= \frac{4\pi R \rho}{M} (\xi_r^2 + \lambda \xi_h^2) r^2 \quad (6)$$

$$\Rightarrow \frac{M}{4\pi R} \frac{dE}{dx} = (\xi_r^2 + \lambda \xi_h^2) \rho r^2 \quad (7)$$

$$\Rightarrow \int_0^R (\xi_r^2 + \lambda \xi_h^2) \rho r^2 dr = \frac{ME}{4\pi} \quad (8)$$

$$\frac{d\beta}{dx} = \frac{4\pi(\xi_r^2 + (\lambda - 1)\xi_h^2 - 2\xi_r \xi_h) U x^2}{c_1 E} \quad (9)$$

$$= \frac{4\pi}{E} \frac{4\pi R \rho}{M} (\xi_r^2 + (\lambda - 1)\xi_h^2 - 2\xi_r \xi_h) r^2 \quad (10)$$

$$\Rightarrow \frac{ME}{(4\pi)^2 R} \frac{d\beta}{dx} = (\xi_r^2 + (\lambda - 1)\xi_h^2 - 2\xi_r \xi_h) \rho r^2 \quad (11)$$

Let's pile all this into the definition of the rotational splitting, from Aerts, Christensen-Dalsgaard & Kurtz (2010), eq. (3.354),

$$\delta\omega = m \int_0^R J \Omega dr \quad (12)$$

where

$$J = \frac{(\xi_r^2 + (\lambda - 1)\xi_h^2 - 2\xi_r \xi_h) \rho r^2}{\int_0^R (\xi_r^2 + \lambda \xi_h^2) \rho r^2} \quad (13)$$

$$= \frac{ME}{(4\pi)^2 R} \frac{d\beta}{dx} \cdot \frac{4\pi}{ME} \quad (14)$$

$$= \frac{1}{4\pi R} \frac{d\beta}{dx} \quad (15)$$

The factor  $R$  is, I believe, absorbed by the fact that the integral is taken over  $x$  rather than  $R$ . That leaves just the factor  $4\pi$ , which is what I've found by inserting a constant rotation rate  $2\pi \text{ rad.s}^{-1}$  into a Sun-like model.